

Program of the Conference

8 – 10 october 2024 50, Svetlanskaya Street, Vladivostok

8 october 2024

- 9.00 10.00 Registration of conference participants
- 10.00 10.15 Opening of the International Conference on Ocean Study 2024. Dolgikh Grigorii, academician of RAS
- 10.15 10.45Plenary report Konoplin Alexandr, director of Academician M. D. Ageev Institute of Marine
Technology Problems Far Eastern Branch of RAS (IMTP FEB RAS)
- 10.45 11.15 Plenary report Rodionov Alexandr, scientific director of the hydroacoustic communications and navigations laboratory of IMTP FEB RAS
- 11.15 11.30 Video about the World Ocean exploration

Break until 14-00

Section **Deep Ocean Research, Oceanography and Marine Environment** (Section Chairman Dr. Alexander Rodionov)

- 14-00 14.15 Olga Trusenkova *, Elena Kustova *The summer reversal of the East Kamchatka Current from satellite altimetry data* (V.I. Il'ichev Pacific Oceanological Institute FEB RAS)
 14.15 14.30 Zhanna Tskhay*, Viktor Filatov Spatial and temporal variations in thermal conditions during the saury fishery in the NorthWest Pacific based on satellite data (Sakhalin branch of "VNIRO")
- 14.30 14.45 Sergey Kasatkin*, Nadezhda Zlobina *Application of Secondary Spectral Analysis for Hydroacoustic Signal Processing* (IMTP FEB RAS)
- 14.45 15.00 Filipp Belchenko*, Ivan Ermolov, Georgij Nagajcev, Artem Sukhanov, Pavel Ostrikov Comparison of UAVs' Trajectories for Sea Surface Survey within Fish Search (IPMech RAS)
 15.00 - 15.15 Dmitry Gryazin*, Olga Belova Metrological support of wave meters based on hydrodynamic
 - pressure sensors (Concern CSRI Elektropribor, JSC ITMO University)

Coffee break

Section Complex Mathematical Problems of Ocean Monitorin	g and Modeling
(Section Chairman Dr. Alexander Inzartsev)	

- 16.00 16.15 Sergey Dyakov*, Marina Aleksanina, Anton Karnatskiy Calculation of Drift Velocities and Compression/Rarefaction Zones of the Sea Ice Cover on Satellite Images of the KMSS/Meteor-M Device (IACP FEB RAS)
- 16.15 16.30 Sergey Dyakov*, Marina Aleksanina, Anton Karnatskiy Calculation of Compositional Maps of Sea Surface Temperature from IR Measurements of US Satellites (IACP FEB RAS)
- 16.30 16.45 Alexey Ermoshkin*, Nikolay Bogatov, Ivan Kapustin, Aleksandr Molkov A Physical Based Method for Retrieval Ocean Currents and Significant Wave Height Using Doppler Marine Radar (A.V. Gaponov-Grekhov Institute of Applied Physics of the RAS)
- 16.45 17.00 Iman Valizadeh*, Jaime Lloret_Mauri *Multi-hop Communication for Underwater Wireless* Sensor Networks (Valencia Polytechnic University)

9 october 2024

09.30 - 10.00 Registration of conference participants

Section Unmanned Marine Vehicles and Systems

(Section Chairman PhD Alexander Konoplin)

- 10.00 10.15 Valeriy Knyazhev *Fuel Cells for AUV Power Supply* (IMTP FEB RAS)
- 10.15 10.30 Mikhail Belousov*, Dmitry Yukhimets, Anton Gubankov Development of Information-Control System for Unmanned Underwater Vehicle by Means of ROS2 (IMPP FEB RAS, IACP FEB RAS, Sevastopol State University, Admiral G.I. Nevelskoy Maritime State University)
- 10.30 10.45 Anastasia Shupikova*, Valeriy Bobkov, Alexander Inzartsev *A Method for Underwater Pipeline Tracking from Stereo Images* (IMTP FEB RAS, IACP FEB RAS)
- 10.45 11.00Valeriy Knyazhev*, Vladimir Loshchenkov Storage of Reagents for Fuel Cells in the AUV (IMTP
FEB RAS)
- 11.00 11.15Nikita Krasavin*, Alexander Konoplin The Underwater Manipulator Position Correction
Method for Performing Contact Operations (IMTP FEB RAS)

Coffee break

Section Navigation and Motion Control (Section Chairman PhD Fedor Dubrovin)

- 12.00 12.15 Fedor Dubrovin On Determining the Spatial Orientation of a Marine Navigation Platform Based on Spatial Orientation Measurements of a Pair of Non-Collinear Measurement Bases (IMTP FEB RAS)
- 12.15 12.30 Sergey Fadyushin*, Alexander Lentarev, Elena Vereschaginan, Yana Pafnuteva, Alexander Tretyak, Sergey Pashin Conceptual Fundamentals of the Symbiotic Partnership in the Course of Controlling ManMachine Systems of the Navigator-Ship Type (FEFU)
- 12.30 12.45 Dmitry Yukhimets *The AUV Control System for Trajectory Movement Taking into Account the Limitations of its Thruster System* (IACP FEB RAS)
- 12.45 13.00 Igor Gornostaev*, Anton Gubankov Development of Method of Generating a Reference Movement Speed of a Group of UAVs (IACP FEB RAS, IMTP FEB RAS)
- 13.00 13.15 Alexey Pavlov An approach to debugging control algorithms for an autonomous underwater vehicle during highprecision navigation to port using data from deepsea television cameras (Concern CSRI Elektropribor)

Break until 14-00

Section Underwater Robotics and Systems

(Section Chairman PhD Eduard Mursalimov)

- 14.00 14.15 Vladimir Gerasimov*, Alexey Filozhenko, Anton Komlev Energy Supply Of The Hybrid UUV And Information Exchange With The Onshore Control Post During The Service Of Underwater Mining Complexes (IMTP FEB RAS)
- 14.15 14.30 Vladimir Kostenko*, Nikolai Naidenko, Roman Vasilenko Approach to the Development of a Steering Thruster Mathematical Model for the Dynamic Positioning Mode of an AUV Equipped with Manipulator (IMTP FEB RAS)
- 14.30 14.45Grigorii Eliseenko Information Flows Management in Heterogeneous Communication
Channels Between AUV and Operator (IMTP FEB RAS)
- 14.45 15.00Alexander Yurmanov*, Roman Vasilenko, Maxim Panchuk Algorithm of Underwater Objects
Identification Considering Defects (IMTP FEB RAS)

Coffee break

- 15.30 15.45 Sergey Kasatkin*, Nadezhda Zlobina *Assessment of Own Noise of Uderwater Glider* Equipped with Combined Receivers (IMTP FEB RAS)
- 15.45 16.00 Artemii Mametev*, Alexander Pavin Color Image Segmentation Algorithm for Autonomous Underwater Vehicles (IMTP FEB RAS)
- 16.00 16.15Anna Bykanova*, Jurii Matvienko, Oleg Lvov Development of a Command AUV for
Controlling a Group of Hybrid AUVs for Operational Noise Field Monitoring Station (IMTP FEB
RAS)
- 16.15 16.30 Maxim Ivanov*, Oleg Stepanov, Valerii Zolotarevich, Andreii Motorin *Recursive and Nonrecursive Passive Target Localization Algorithms with Bearing-Only Measurements* (ITMO University, Concern CSRI Elektropribor, JSC)
- 16.30 16.45Iman Valizadeh*, Jaime Lloret_Mauri Localization Techniques in Underwater Wireless Sensor
Networks (Valencia Polytechnic University)

10 october 2024

13-30 - 14.00 Registration of conference participants

Section Underwater Robotics and Systems

(Section Chairman PhD Alexander Pavin)

- 14.00 14.15Vladimir Kostenko Calculation and Experimental Methodology for Assessing the Autonomy
Parameters of the AUV (IMTP FEB RAS)
- 14.15 14.30Vladislav Mikhailov*, Vladimir Gerasimov Development of a Cable Communication System
for an Underwater Vehicle with a Bottom Station (IMTP FEB RAS)
- 14.30 14.45 Konstanin Shilin*, Alexander Pavin *Light Neural Network for Pipeline Segmentation on a Side-Scan Sonar Images* (IMTP FEB RAS)
- 14.45 15.00 Alexander Protsenko*, Aleksey Kabanov, Alexander Zuev, Alexey Zhirabok The Optimal Astatic Observer for the Identification of Disturbances in Nonlinear Robotic Systems (IACP FEB RAS)
- 15.00 15.15Alexander Torzhkov*, Grigorii Eliseenko, Alexander Pavin Using Python to Create Control
Systems for Unmanned Underwater Vehicles (IMTP FEB RAS)
- 15.15 15.30Andrei Medvedev*, Vladimir Kostenko, Irina Mokeeva Modeling the Movement of a ROV
Taking into Account the Influence of a Communication Cable (IMTP FEB RAS)
- 15.30 15.45 Mikhail Panin*, Valery Bobkov, Mikhail Morozov, Alexander Inzartsev AUV Inspection of Subsea Pipelines Using Information from an Onboard Stereo Camera (IMTP FEB RAS, IACP FEB RAS)
- 16.00 16.15 Closing of the International Conference on Ocean Studies 2024 Final speech Rodionov Alexander
- 16.15 19.00 Final lanch